

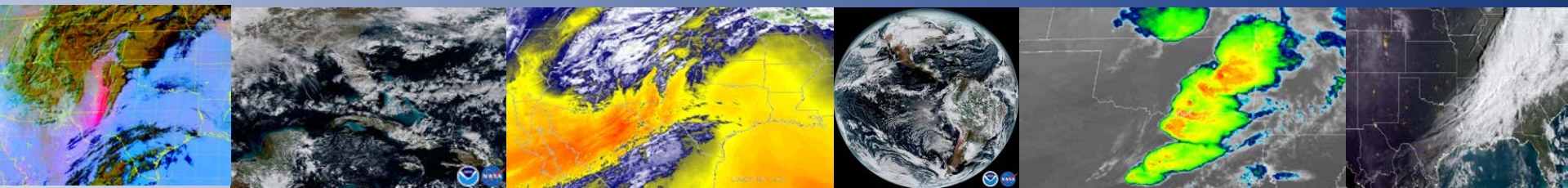
Geostationary Lightning Mapper: Introduction and Overview

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A Short Outline

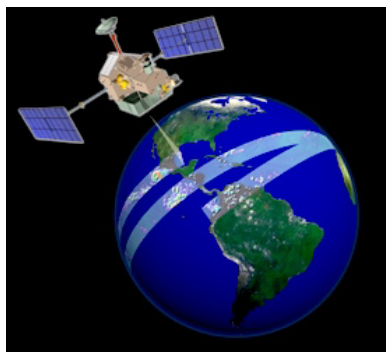
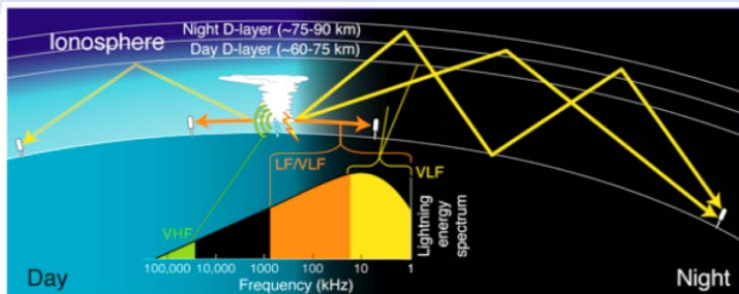
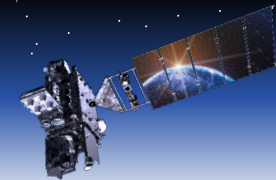


Today for the Geostationary Lightning Mapper (GLM):

- Detecting lightning and what is total lightning?
- What is the Geostationary Lightning Mapper?
- Why is it important?
- Basic GLM observations
- Two short, hands-on activities after this introduction
 - Severe weather event
 - Lightning safety event



Lightning Detection Methods

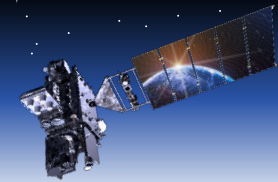


- Ground-based lightning detection networks observe radio waves generated by lightning (low to very high frequency)
 - Most primarily observe cloud-to-ground
 - Work best with numerous sensors
- Space-based lightning sensors observe optical emissions from lightning at cloud top
 - All low Earth orbiters prior to GOES-16
 - Best detection at night, but advances (such as with GOES-16) have greatly improved daytime detection

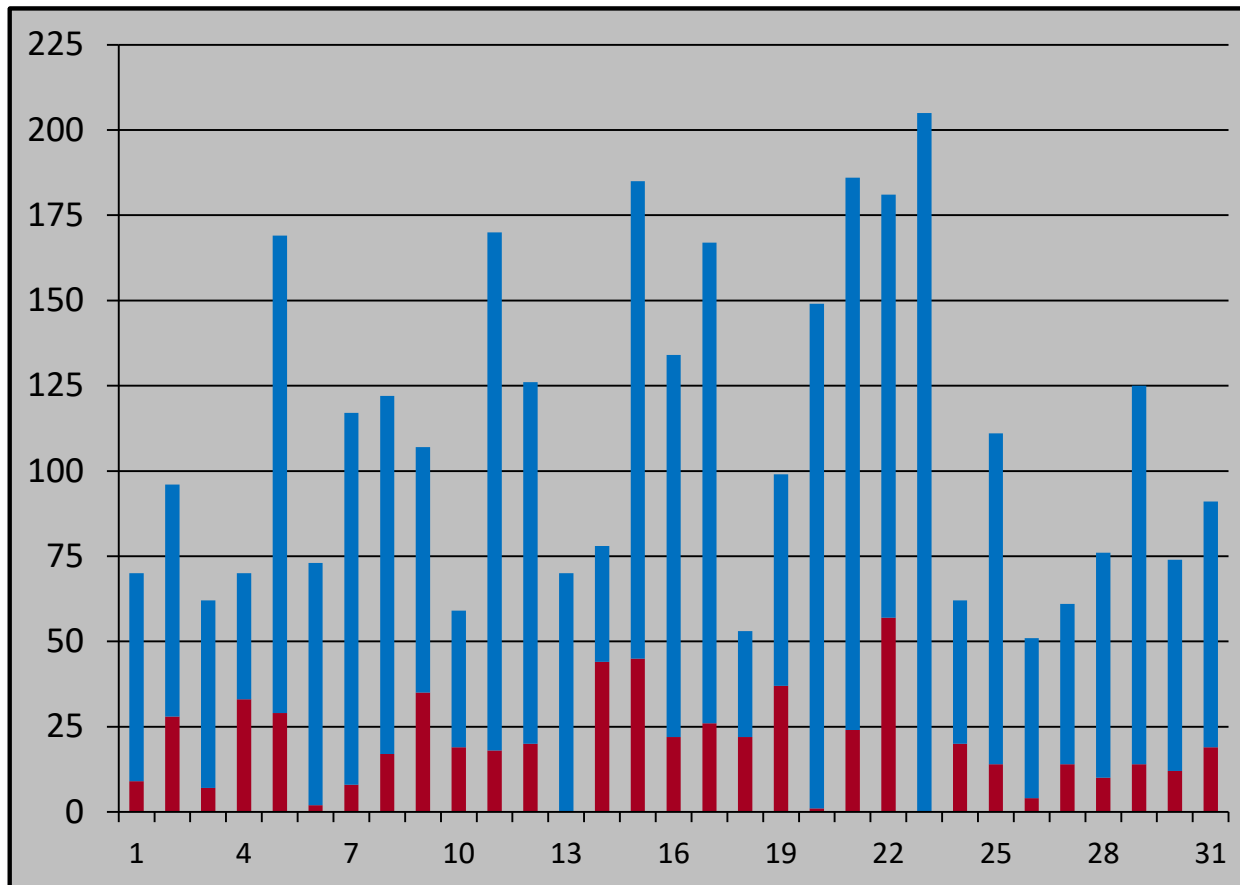




Total Lightning



Total Lightning Activity



31 Individual Storms

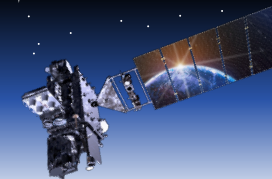
Cloud-to-Ground
Strikes

Inter-Cloud
Flashes

- Combination of cloud-to-ground and intra-cloud observations
- Intra-cloud typically far outnumbers cloud-to-ground in any given storm
- Provides several capabilities ...

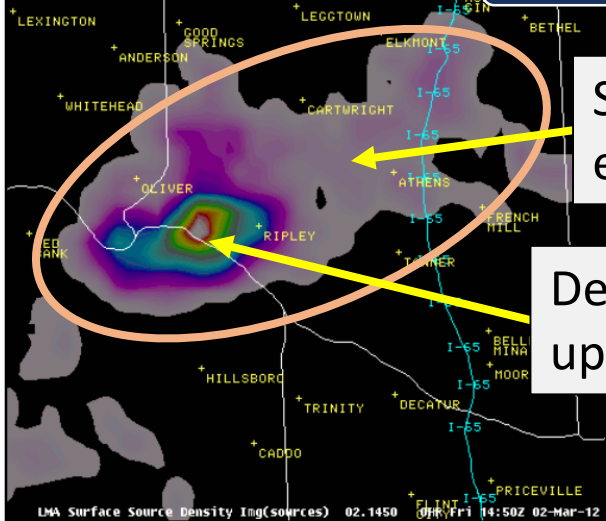


Total Lightning ... In a Flash



Total Lightning

1450 UTC

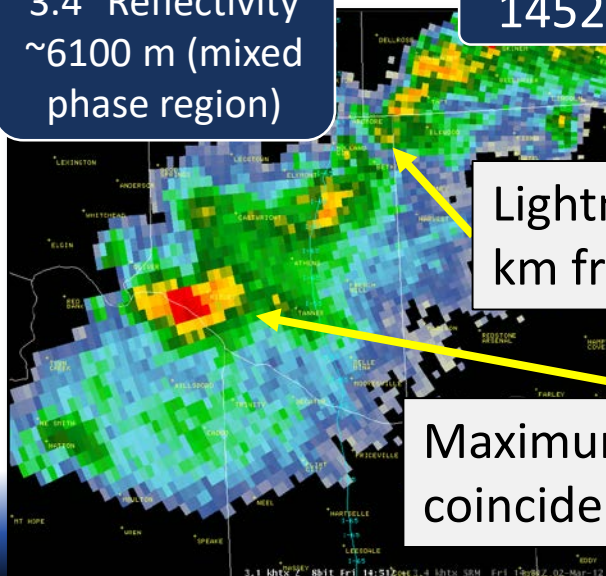


Spatial extent

Developing updraft

3.4° Reflectivity
~6100 m (mixed phase region)

1452 UTC



Lightning 10s of km from updraft

Maximum of lightning coincident with updraft

Physical Reasoning

- Updraft in mixed phase region (above -10°C)
- Stronger, deeper updraft = More lightning
- Increase = Strengthening updraft

Applications

- Rapid increases = Lightning jumps (potential for severe weather)
- Safety: Extent / lead time on first CG
- Aviation: Monitor convection

Key to Training

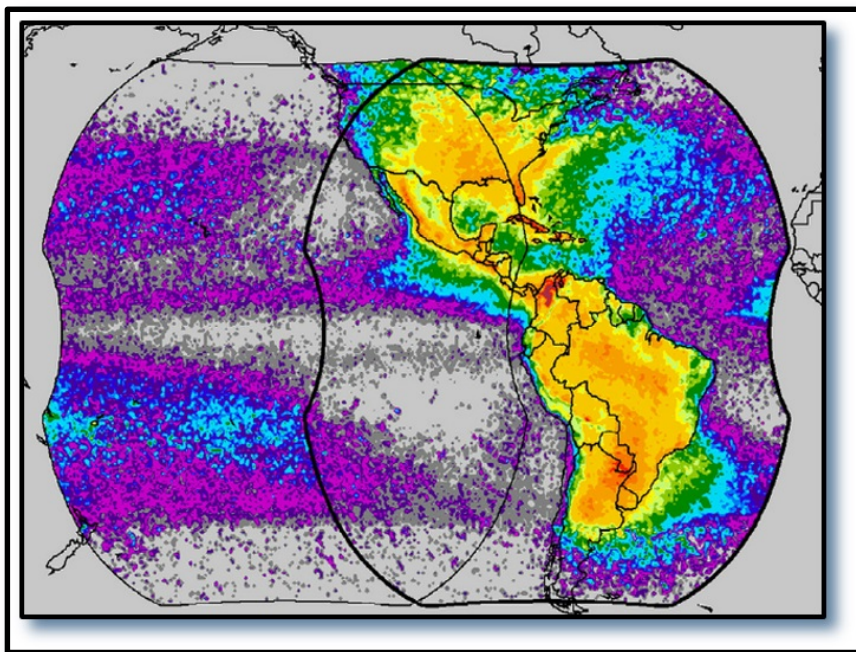
- Connect GLM to radar in order to fit conceptual model



Geostationary Lightning Mapper



GLM field of view for initial calibration and validation

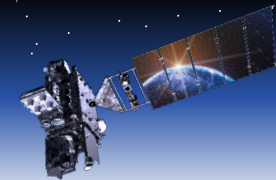


Lightning climatology from OTD and TRMM-LIS (1995-2005)

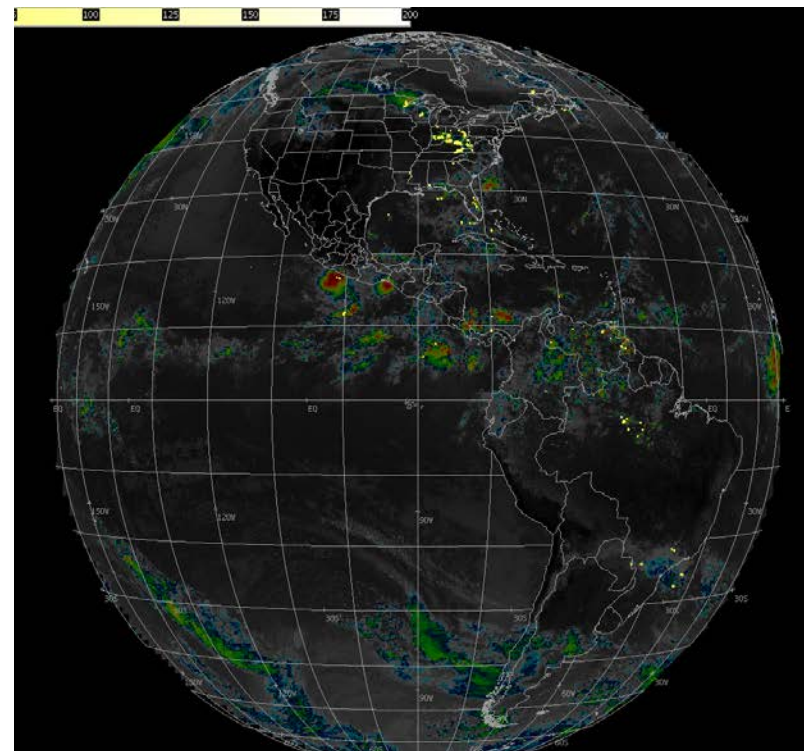
- Large digital camera to detect cloud top brightness differences per pixel
- 8 km at nadir to 14 km at the edge
- Intra-cloud and cloud-to-ground obs
 - Does **NOT** distinguish the difference
- GOES-16 is first to carry GLM
 - Available through 2036 with GOES-U
- Specifications:
 - 70% total flash detection over 24 hours over entire field of view
 - 5% false alarm rate
 - GLM is likely to exceed design specs



Why Have the GLM?



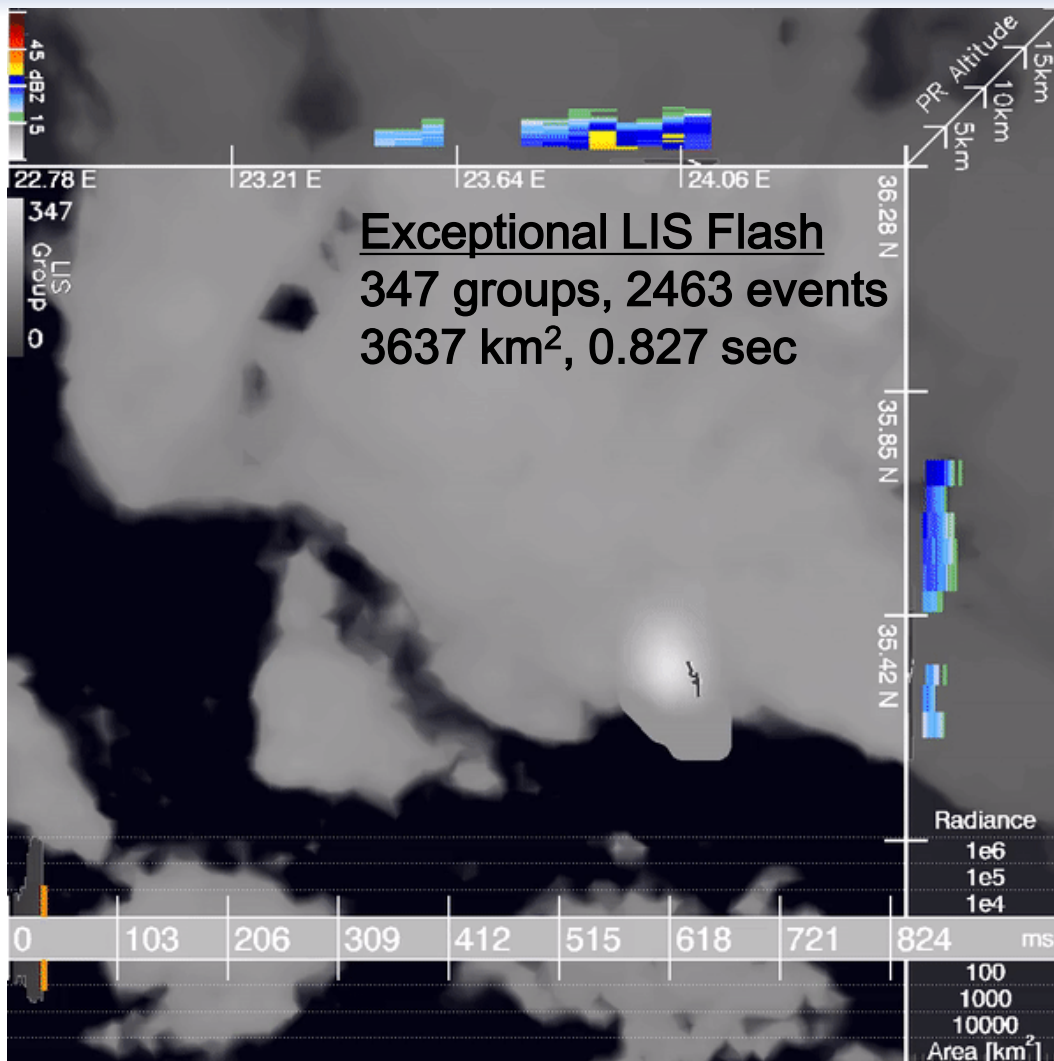
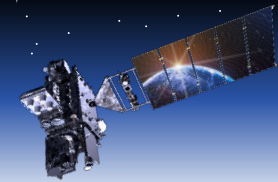
- Continuous full disk total lightning observations
 - 54° N/S with 20 second latency
 - Valuable in data sparse regions, especially to supplement radar
- Intra-cloud typically precedes cloud-to-ground
- Areal extent of the lightning threat
- Monitor convection
 - Track cells embedded in larger features
 - Monitor storm strength
 - Identify convective cells
- Insights into tropical cyclone intensity



Example animation of GLM over the full disk.



GLM Detection Methodology

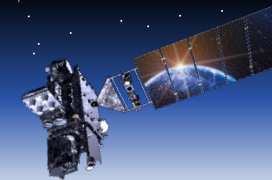


- GLM produces a background image every 2 min
- Each pixel “looks” for changes in brightness versus the background
 - Every 2 ms
 - Illuminated pixel is an “Event”
- Quality controls reduce noise
- Events basis for derived observations
 - Groups and flashes (next slide)
- Also observe optical power
 - Future research activity

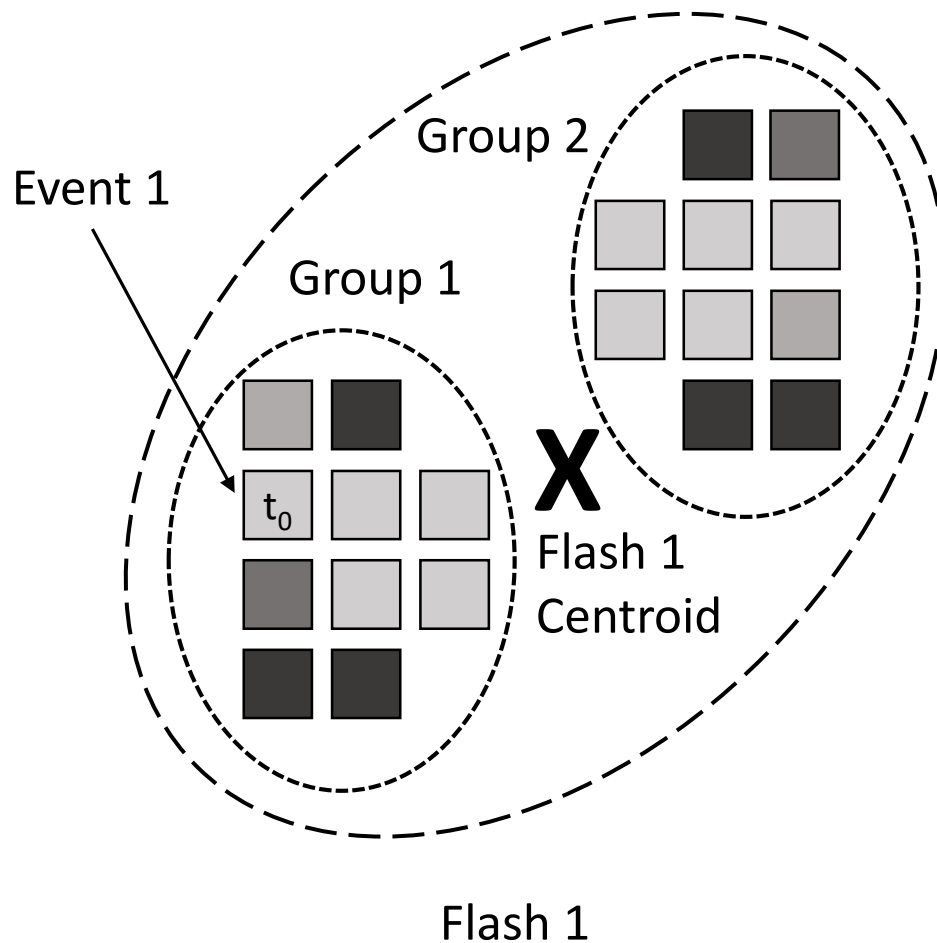
Demo of how lightning is viewed by the GLM using TRMM-Lightning Imaging Sensor observations



GLM Observation Definitions

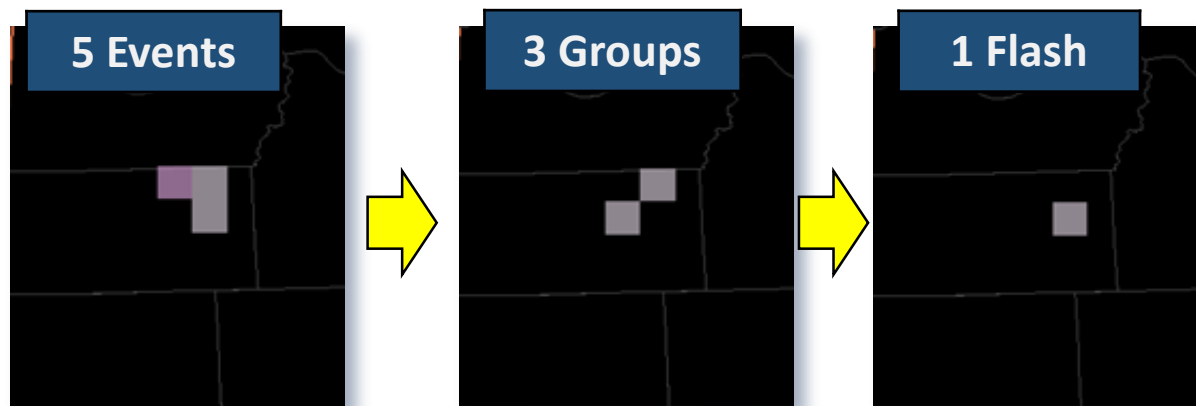


A lightning flash as viewed from space.





GLM Observation Definitions



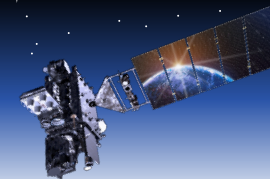
Event: Any illuminated pixel in 2 ms period that exceeds the background threshold.

Group Centroid: Optically weighted cluster of events in time and space. Equivalent to return strokes.

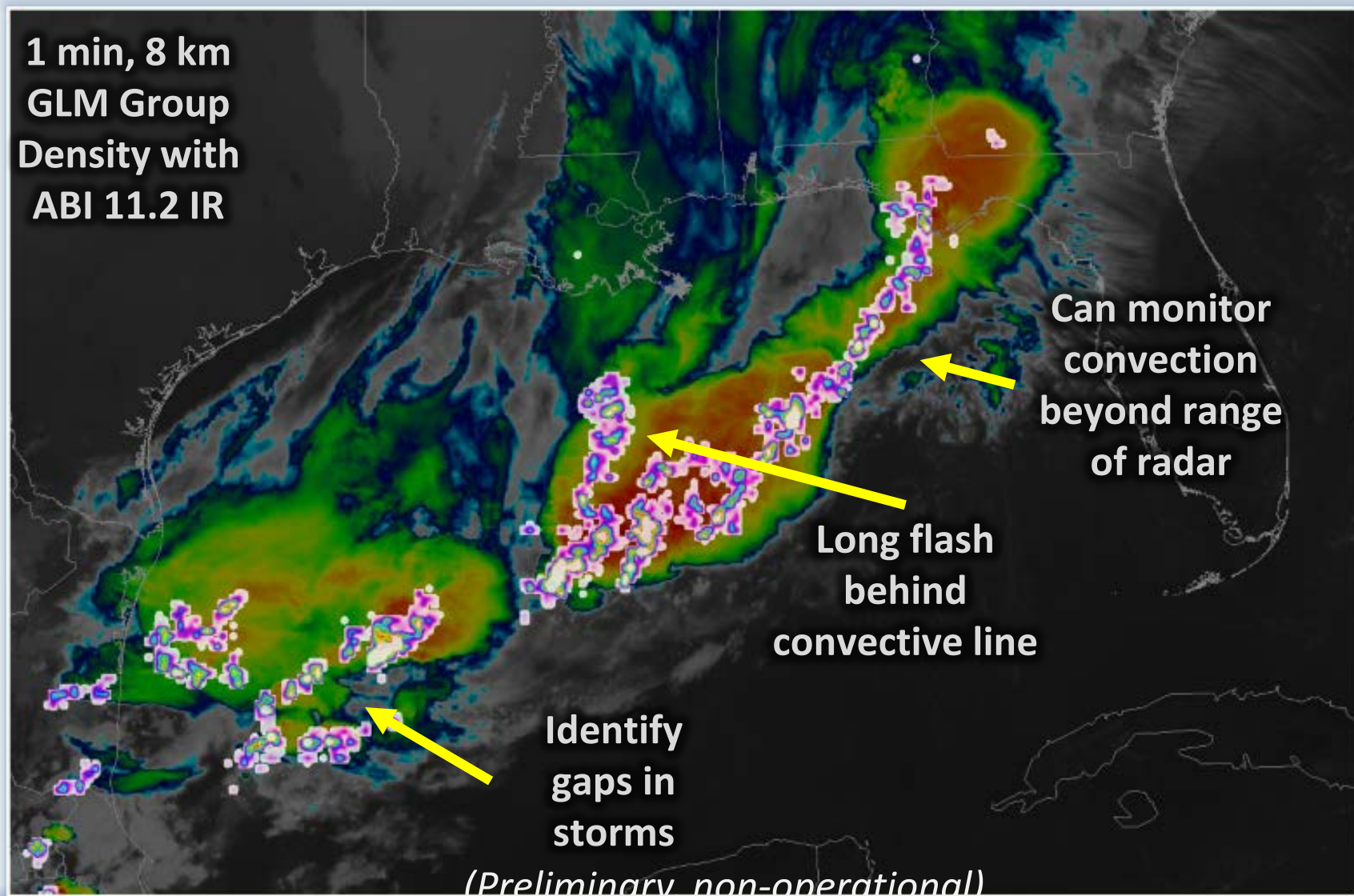
Flash Centroid: Optically weighted cluster of groups (based on events) in time and space separated by less than 330 ms and 16.5 km.



GLM Example Image

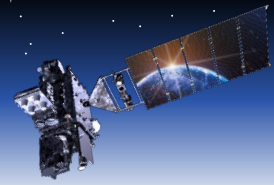


**1 min, 8 km
GLM Group
Density with
ABI 11.2 IR**





Summary / Discussion



- GOES-16 GLM is the first lightning mapper in geostationary orbit
- Provides continuous, full disk total lightning measurements
- GLM observes optical emissions of lightning from the cloud top
 - Reports events, groups, and flashes
- Wide range of operational applications
 - Severe weather decision support
 - Lightning safety
 - Aviation and tropical meteorology applications
- GLM has a tremendous variety of efforts for new research

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